Model Order Reduction for Nonlinear Radiative Transfer Based on Moment Equations and Data-Driven Approximations of the Eddington Tensor

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Outline

- Fundamental approach and basic ideas
 - Model order reduction for Boltzmann transport problems
 - Thermal radiative transfer (TRT) problems
 - Nonlinear projective approach
- Derivation of multilevel low-order Quasidiffusion (Variable Eddington Factor) equations for the Boltzmann transport equation (BTE)
- Formulation of data-driven ROMs for nonlinear TRT problems with POD and DMD of the Eddington tensor
- Numerical results for multigroup TRT problems in 2D Cartesian geometry
- Discussion
- This is a joint work with Dmitriy Anistratov (NCSU)

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- Radiative transfer is the physical process of energy transfer via the propagation, emission and absorption of photon radiation in the host medium
- Radiative transfer becomes the dominant mode of energy redistribution in materials at extreme temperatures, and is an essential piece of physics for many phenomena spanning several fields
 - plasma physics
 - high-energy density physics
 - astrophysics
 - atmospheric science
- These phenomena are described by complex multiphysical systems of differential equations (radiation hydrodynamics)
- The particle transport physics is modeled by the Boltzmann transport equation (BTE)

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Challenges in Simulation of Particle Transport Problems

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- The numerical simulation of mutiphysical particle transport problems faces several challenges
 - High-dimensionality
 - Strong nonlinearity
 - Strong coupling of equations
 - Material opacities depend on state of matter
 - The state of matter is influenced by particle fluxes
 - Multi-scale characterization
 - Distinct characteristic behavior in different energy ranges
 - System of equations of different types
 - Integro-differential BTE
- The BTE is especially challenging to solve
 - Hyperbolic differential operator
 - The solution at any point depends on the solution everywhere in phase space due to the integral operator
 - The solution is high-dimensional

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Model Order Reduction for the BTE

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- The BTE largely influences the dimensionality of these problems
 - 3D geometry \rightarrow 7 independent variables
- Reduced order models (ROMs) for the BTE are commonly employed to reduce the cost of multiphysics simulations involving radiative transfer
- Some ROMs have seen widespread adoption for their usefulness and simplicity
 - Diffusion-based models like flux limited diffusion (FLD)
 - P₁, P_{1/3}, P₃
 - Minerbo models
- However, the accuracy of these models is limited
- The development of *advanced* ROMs for the BTE that can achieve both computational efficiency and high accuracy is an active field of research
 - In recent times the bulk of this research effort has been focused on data-driven ROMs

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Data-Driven Model Order Reduction for the BTE

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- The most advanced methods for data-driven model order reduction were developed with fluid dynamics in mind
- More recently these methods have been the subject of a substantial research effort for developing ROMs for Boltzmann transport
- The majority of these ROMs focus on linear particle transport problems
- Many questions remain for nonlinear problems of high energy density physics (radiation hydrodynamics problems)
 - How to preserve and reproduce essential features of fundamental physics
 - Dealing with multiscale behavior

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Fundamental Approach

Nonlinear projective approach

- interpretation
 - nonlinear method of moments
 - multigrid approach
- Known to give advantage in multiphysical, multiscale applications
- The BTE is coupled with a hierarchy of low-order moment equations
 - Each moment system is exactly closed through nonlinear functionals of the BTE solution (e.g. the Eddington tensor)
 - Moment equations are conservation equations for integral (low-dimensional) quantities
 - Moment equations account for different scales of the problem
 - Multiphysics equations are coupled to moment equations on the same dimensional scale
- Data-driven methods of approximation to estimate closures for low-order equations
 - proper orthogonal decomposition (POD)
 - dynamic mode decomposition (DMD)
 - Fundamental radiation physics conserved through moment equations

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Nonlinear Thermal Radiative Transfer Problem

- Prototypes of these ROMs are designed for the fundamental thermal radiative transfer (TRT) problem
 - Supersonic radiation flow problem neglecting material motion, photon scattering, heat conduction and external sources
- The high-order multigroup Boltzmann transport equation (BTE)

$$\frac{1}{c} \frac{\partial I_g(\mathbf{r}, \Omega, t)}{\partial t} + \Omega \cdot \nabla I_g(\mathbf{r}, \Omega, t) + \varkappa_g(T) I_g(\mathbf{r}, \Omega, t) = \varkappa_g(T) B_g(T)$$

$$\stackrel{\partial G}{\underset{G}{\longrightarrow}} \mathbf{r} \in G, \text{ for all } \Omega, \quad g = 1, \dots, N_g, \quad t \ge t_0,$$

$$I_g|_{\mathbf{r} \in \partial G} = I_g^{in}, \quad \Omega \cdot \mathbf{e}_n < 0, \quad t \ge t_0,$$

$$I_g|_{t=t_0} = I_g^0, \quad \mathbf{r} \in G, \text{ for all } \Omega,$$

- **r** spatial position, Ω direction of particle motion, g photon frequency group, t time, $l_g(\mathbf{r}, \Omega, t)$ specific intensity of photons in the group g
- The material energy balance (MEB) equation

$$\frac{\partial \varepsilon(T)}{\partial t} = \sum_{g=1}^{N_g} \int_{4\pi} \varkappa_g(T) \Big(I_g(\mathbf{r}, \Omega, t) - B_g(T) \Big) d\Omega, \quad T|_{t=t_0} = T^0(\mathbf{r}), \text{ for } \mathbf{r} \in G.$$

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Multigroup Quasidiffusion (VEF) Equations

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$$\frac{1}{c}\frac{\partial I_g}{\partial t} + \Omega \cdot \nabla I_g + \varkappa_g(T)I_g = \varkappa_g(T)B_g(T)$$

- Angular moments of intensities
 - $E_g((r), t) = \frac{1}{c} \int_{4\pi} I_g d\Omega$ • $F_g((r), t) = \int_{4\pi} \Omega I_g d\Omega$
- Projection: $\int_{4\pi} \cdot d\Omega = \int_{4\pi} \Omega \cdot d\Omega$

$$\frac{\partial E_g}{\partial t} + \nabla \cdot F_g + c\varkappa_g(T)E_g = 4\pi\varkappa_g(T)B_g(T), \qquad (1)$$
$$\frac{1}{c}\frac{\partial F_g}{\partial t} + c\nabla \cdot \left(f_g[I]E_g\right) + \varkappa_g(T)F_g = 0 \qquad (2)$$

• Exact closure through the Eddington tensor

$$\mathfrak{f}_{g}[I] = \frac{\int_{4\pi} \Omega \otimes \Omega I_{g} d\Omega}{\int_{4\pi} I_{g} d\Omega} \tag{(}$$

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Multigroup Quasidiffusion (VEF) Equations

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• Projection: $\int_{4\pi} \cdot d\Omega = \int_{4\pi} \Omega \cdot d\Omega$

$$\frac{\partial E_g}{\partial t} + \boldsymbol{\nabla} \cdot \boldsymbol{F}_g + c \varkappa_g(T) E_g = 4\pi \varkappa_g(T) B_g(T), \qquad (1)$$

$$\frac{1}{c}\frac{\partial \boldsymbol{F}_g}{\partial t} + c\boldsymbol{\nabla}\cdot\left(\boldsymbol{\mathfrak{f}}_g[\boldsymbol{I}]\boldsymbol{E}_g\right) + \varkappa_g(\boldsymbol{T})\boldsymbol{F}_g = 0 \tag{2}$$

Exact closure through the Eddington tensor

$$\mathfrak{f}_{g}[l] = \frac{\int_{4\pi} \Omega \otimes \Omega I_{g} d\Omega}{\int_{4\pi} I_{g} d\Omega} \tag{3}$$

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Multigroup Quasidiffusion (VEF) Equations

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$$\frac{1}{c}\frac{\partial I_g}{\partial t} + \Omega \cdot \nabla I_g + \varkappa_g(T)I_g = \varkappa_g(T)B_g(T)$$

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Exact closure through the Eddington tensor

$$\mathfrak{f}_{g}[I] = \frac{\int_{4\pi} \Omega \otimes \Omega I_{g} d\Omega}{\int_{4\pi} I_{g} d\Omega}$$
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Effective Grey Quasidiffusion (VEF) Equations

$$\frac{\partial E_g}{\partial t} + \nabla \cdot \boldsymbol{F}_g + c \varkappa_g(T) E_g = 4\pi \varkappa_g(T) B_g(T),$$

$$\frac{1}{c} \frac{\partial \boldsymbol{F}_g}{\partial t} + c \nabla \cdot \left(f_g[I] E_g \right) + \varkappa_g(T) \boldsymbol{F}_g = 0$$
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• Frequency-integrated angular moments of intensities

•
$$E = \sum_{g=1}^{N_g} E_g$$
, $F = \sum_{g=1}^{N_g} F_g$
• Projection: $\sum_{g=1}^{N_g} \cdot$
 $\frac{\partial E}{\partial t} + \nabla \cdot F + c\bar{\varkappa}_E E = c\bar{\varkappa}_B a_R T^4$ (4)
 $\frac{1}{c} \frac{\partial F}{\partial t} + c \nabla \cdot (\bar{\mathfrak{f}} E) + \bar{K}_R F + \bar{\eta} E = 0$ (5)

Exact closure through frequency-averaged grey factors

$$\bar{\varkappa}_{E} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} E_{g}}{\sum_{g=1}^{N_{g}} E_{g}}, \quad \bar{\varkappa}_{B} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} B_{g}}{\sum_{g=1}^{N_{g}} B_{g}}, \quad \bar{\varkappa}_{R,\alpha} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} |F_{\alpha,g}|}{\sum_{g=1}^{N_{g}} |F_{\alpha,g}|}, \quad (6)$$
$$\mathcal{K}_{R} = \operatorname{diag}(\bar{\varkappa}_{R,\varkappa}, \bar{\varkappa}_{R,y}, \bar{\varkappa}_{R,z}), \quad \bar{\mathfrak{f}} = \frac{\sum_{g=1}^{N_{g}} \mathfrak{f}_{g} E_{g}}{\sum_{g=1}^{N_{g}} E_{g}}, \quad \bar{\eta} = \frac{\sum_{g=1}^{N_{g}} (\varkappa_{g} - \bar{\mathcal{K}}_{R}) \mathcal{F}_{g}}{\sum_{g=1}^{N_{g}} E_{g}}. \quad (7)$$

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Effective Grey Quasidiffusion (VEF) Equations

$$\frac{\partial E_g}{\partial t} + \nabla \cdot \boldsymbol{F}_g + c \varkappa_g(T) E_g = 4\pi \varkappa_g(T) B_g(T),$$

$$\frac{1}{c} \frac{\partial \boldsymbol{F}_g}{\partial t} + c \nabla \cdot \left(f_g[I] E_g \right) + \varkappa_g(T) \boldsymbol{F}_g = 0$$
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Frequency-integrated angular moments of intensities

•
$$E = \sum_{g=1}^{N_g} E_g$$
, $F = \sum_{g=1}^{N_g} F_g$

• Projection: $\sum_{g=1}^{N_g} \cdot \frac{\partial E}{\partial t} + \nabla \cdot F + c \bar{\varkappa}_E E = c \bar{\varkappa}_B a_R T^4$ (4) $\frac{1}{c} \frac{\partial F}{\partial t} + c \nabla \cdot (\bar{\mathfrak{f}} E) + \bar{K}_R F + \bar{\eta} E = 0$ (5)

• Exact closure through frequency-averaged grey factors

$$\bar{\varkappa}_{E} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} E_{g}}{\sum_{g=1}^{N_{g}} E_{g}}, \quad \bar{\varkappa}_{B} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} B_{g}}{\sum_{g=1}^{N_{g}} B_{g}}, \quad \bar{\varkappa}_{R,\alpha} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} |F_{\alpha,g}|}{\sum_{g=1}^{N_{g}} |F_{\alpha,g}|}, \quad (6)$$

$$\mathcal{K}_{R} = \operatorname{diag}(\bar{\varkappa}_{R,\varkappa}, \bar{\varkappa}_{R,y}, \bar{\varkappa}_{R,z}), \quad \bar{\mathfrak{f}} = \frac{\sum_{g=1}^{N_{g}} \mathfrak{f}_{g} E_{g}}{\sum_{g=1}^{N_{g}} E_{g}}, \quad \bar{\eta} = \frac{\sum_{g=1}^{N_{g}} (\varkappa_{g} - \bar{K}_{R}) F_{g}}{\sum_{g=1}^{N_{g}} E_{g}}. \quad (7)$$

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Multilevel Quasidiffusion Method

- High-order Boltzmann transport equation for I_g $\frac{1}{c} \frac{\partial I_g}{\partial t} + \Omega \cdot \nabla I_g + \varkappa_g(T) I_g = \varkappa_g(T) B_g(T)$ • Eddington tensor $I_g \Rightarrow f_g[I] = \frac{\int_{4\pi} \Omega \otimes \Omega I_g d\Omega}{\int_{4\pi} I_g d\Omega}$
- Multigroup quasidiffusion equations for E_g , F_g

$$\begin{aligned} \frac{\partial E_g}{\partial t} + \boldsymbol{\nabla} \cdot \boldsymbol{F}_g + c \varkappa_g(T) E_g &= 4\pi \varkappa_g(T) B_g(T), \\ \frac{1}{c} \frac{\partial \boldsymbol{F}_g}{\partial t} + c \boldsymbol{\nabla} \cdot \left(\mathbf{f}_g[I] E_g \right) + \varkappa_g(T) \boldsymbol{F}_g &= 0 \end{aligned}$$

- Grey closures E_g , $F_g \Rightarrow \bar{\varkappa}_E$, $\bar{\varkappa}_B$, $\bar{\mathfrak{f}}$, \bar{K}_R , $\bar{\eta}$
- Effective grey problem for E, F, T

$$\frac{\partial E}{\partial t} + \nabla \cdot F + c\bar{\varkappa}_E E = c\bar{\varkappa}_B a_R T^4$$
$$\frac{1}{c} \frac{\partial F}{\partial t} + c\nabla \cdot (\bar{\mathfrak{f}}E) + \bar{K}_R F + \bar{\eta}E = 0$$
$$\frac{\partial \varepsilon(T)}{\partial t} = c(\bar{\varkappa}_E E - \bar{\varkappa}_B a_R T^4)$$

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$$\bar{\varkappa}_{E} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} E_{g}}{\sum_{g=1}^{N_{g}} E_{g}}$$

$$\bar{\varkappa}_B = \frac{\sum_{g=1}^{N_g} \varkappa_g B_g}{\sum_{g=1}^{N_g} B_g}$$

$$\bar{\varkappa}_{R,\alpha} = \frac{\sum_{g=1}^{N_g} \varkappa_g |F_{\alpha,g}|}{\sum_{g=1}^{N_g} |F_{\alpha,g}|}$$

$$\mathbf{K}_{\mathbf{R}} = \operatorname{diag}(\bar{\varkappa}_{R,x}, \bar{\varkappa}_{R,y}, \bar{\varkappa}_{R,z})$$

$$\bar{\mathfrak{f}} = \frac{\sum_{g=1}^{N_g} \mathfrak{f}_g E_g}{\sum_{g=1}^{N_g} E_g}$$

$$ar{m{\eta}} = rac{\sum_{g=1}^{N_g} (arkappa_g - ar{m{K}}_{m{R}}) m{F}_{g}}{\sum_{g=1}^{N_g} m{E}_{g}}$$

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Reduced-Order Model for TRT

Data-driven approximator

 $ilde{\mathfrak{f}}_{g}=\mathcal{G}[\mathfrak{f}^{*}], \quad \mathfrak{f}^{*}$ known

 $\bullet~$ Multigroup quasidiffusion equations for $\textit{E}_{g},~\textit{F}_{g}$

$$\frac{\partial E_g}{\partial t} + \boldsymbol{\nabla} \cdot \boldsymbol{F}_g + c \varkappa_g(T) E_g = 4\pi \varkappa_g(T) B_g(T),$$
$$\frac{1}{c} \frac{\partial \boldsymbol{F}_g}{\partial t} + c \boldsymbol{\nabla} \cdot \left(\tilde{\boldsymbol{\mathfrak{f}}}_g E_g\right) + \varkappa_g(T) \boldsymbol{F}_g = 0$$

- Grey closures E_g , $F_g \Rightarrow \bar{\varkappa}_E$, $\bar{\varkappa}_B$, $\bar{\mathfrak{f}}$, \bar{K}_R , $\bar{\eta}$
- Effective grey problem for E, F, T

$$\frac{\partial E}{\partial t} + \nabla \cdot F + c\bar{\varkappa}_E E = c\bar{\varkappa}_B a_R T^4$$
$$\frac{1}{c} \frac{\partial F}{\partial t} + c\nabla \cdot (\bar{\mathbf{f}}E) + \bar{\mathbf{K}}_R F + \bar{\eta}E = 0$$
$$\frac{\partial \varepsilon(T)}{\partial t} = c (\bar{\varkappa}_E E - \bar{\varkappa}_B a_R T^4)$$

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$$\bar{\varkappa}_{E} = \frac{\sum_{g=1}^{N_{g}} \varkappa_{g} E_{g}}{\sum_{g=1}^{N_{g}} E_{g}}$$

$$\bar{\varkappa}_B = \frac{\sum_{g=1}^{N_g} \varkappa_g B_g}{\sum_{g=1}^{N_g} B_g}$$

$$\bar{\varkappa}_{R,\alpha} = \frac{\sum_{g=1}^{N_g} \varkappa_g |F_{\alpha,g}|}{\sum_{g=1}^{N_g} |F_{\alpha,g}|}$$

$$\mathbf{K}_{\mathbf{R}} = \operatorname{diag}(\bar{\varkappa}_{R,x}, \bar{\varkappa}_{R,y}, \bar{\varkappa}_{R,z})$$

$$\bar{\mathfrak{f}} = \frac{\sum_{g=1}^{N_g} \mathfrak{f}_g E_g}{\sum_{g=1}^{N_g} E_g}$$

$$ar{m{\eta}} = rac{\sum_{g=1}^{N_g} (arkappa_g - ar{m{K}}_{m{R}}) m{F}_g}{\sum_{g=1}^{N_g} m{E}_g}$$

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Approximation of Eddington Tensor

- Projection, compression of data
 - Given: full-order solution to some TRT problem for N_t time steps, N_g frequency groups, N_r spatial cells
 - Vectors of each Eddington Tensor component at time t^n

$$\mathbf{f}_{\alpha\beta}^{n} \in \mathbb{R}^{N_{r}N_{g}}, \quad \alpha, \beta = x, y, z$$

Construction of snapshot matrices

$$\mathbf{A}^{\mathfrak{f}_{\alpha\beta}} = [\mathbf{f}^1_{\alpha\beta} \ \mathbf{f}^2_{\alpha\beta} \ \dots \ \mathbf{f}^{N_t}_{\alpha\beta}] \in \mathbb{R}^{N_r N_g \times N_t}$$

• Define projection operator \mathcal{G}^k that will project a given matrix **A** onto a rank-k subspace

$$\mathcal{A}_{k}^{\mathfrak{f}_{lphaeta}}=\mathcal{G}^{k}\mathbf{A}^{\mathfrak{f}_{lphaeta}},\quad k\leq ext{rank}(\mathbf{A}^{\mathfrak{f}_{lphaeta}})$$

• $\mathcal{A}_k^{\mathfrak{f}_{\alpha\beta}}$ is constructed of k sets of various vectors and factors

- Approximation of data from rank k representation
 - A map \mathcal{M}^n is defined by the same method used to define \mathcal{G}^k

$$\mathbf{f}_{\alpha\beta}^{n}\approx\mathcal{M}^{n}\mathcal{A}_{k}^{\mathfrak{f}_{\alpha\beta}}$$

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POD of the Eddington Tensor

• Centered data matrix

$\hat{\mathsf{A}}^{\mathsf{f}_{\alpha\beta}} = [\hat{\mathsf{f}}^1_{\alpha\beta}, \dots, \hat{\mathsf{f}}^{N_t}_{\alpha\beta}], \qquad \hat{\mathsf{f}}^n_{\alpha\beta} = \mathsf{f}^n_{\alpha\beta} - \bar{\mathsf{f}}_{\alpha\beta}, \qquad \bar{\mathsf{f}}_{\alpha\beta} = \frac{1}{N_t} \sum_{n=1}^{N_t} \mathsf{f}^n_{\alpha\beta}$

 $\bullet\,$ A thin singular value decomposition (SVD) represents the matrix in the form

$$\hat{\mathsf{A}}^{\mathfrak{f}_{lphaeta}} = \mathsf{U}\mathsf{S}\mathsf{V}^{\mathsf{T}},$$

$$\begin{split} & \textbf{U} \in \mathbb{R}^{N_{r}N_{g},d} \text{ holds the left singular vectors } \{ \textbf{\textit{u}}_{\ell} \}_{\ell=1}^{d} \text{ in its columns} \\ & \textbf{V} \in \mathbb{R}^{N_{t},d} \text{ holds the right singular vectors } \{ \textbf{\textit{v}}_{\ell} \}_{\ell=1}^{d} \text{ in its columns} \\ & \textbf{S} \in \mathbb{R}^{d,d} \text{ holds the singular values } \{ \sigma_{\ell} \}_{\ell=1}^{d} \text{ along its diagonal in decreasing order,} \end{split}$$

$$d = \operatorname{rank}(\hat{\mathbf{A}}^{\mathfrak{f}_{lphaeta}}) = \min(N_r N_g, N_t)$$

• The rank-k POD representation of $f_{\alpha\beta}$

$$\mathcal{A}_{k}^{\mathfrak{f}_{\alpha\beta}} = \overline{\mathbf{f}}_{\alpha\beta} \cup \{\sigma_{\ell}, \mathbf{u}_{\ell}, \mathbf{v}_{\ell}\}_{\ell=1}^{k}$$

$$\tilde{\mathbf{f}}_{\alpha\beta}^{n} \leftarrow \bar{\mathbf{f}}_{\alpha\beta} + \sum_{\ell=1}^{k} \sigma_{\ell}(\mathbf{v}_{\ell})_{n} \mathbf{u}_{\ell} = \mathcal{M}^{n} \mathcal{A}_{k}^{\mathbf{f}_{\alpha\beta}}$$

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DMD of the Eddington Tensor

 The DMD constructs the best-fit linear operator B to the time-dependent data {fⁿ_{αβ}}^{Nt}_{n=1}, generating the dynamic system:

$$rac{d ilde{{f f}}_{lphaeta}(t)}{dt}={f B} ilde{{f f}}_{lphaeta}(t), \ \ \Rightarrow \ \ \ ilde{{f f}}_{lphaeta}(t)=\sum_{\ell=1}^keta_\ellarphi_\ell{f e}^{\omega_\ell t},$$

 $\omega_\ell, \pmb{\varphi}_\ell$ are the eigenvalues and associated eigenfunctions of \bm{B}

- Form two data matrices for $t^n = t^{n-1} + \Delta t$ with constant time step $\mathbf{X}_{\alpha\beta} = [\mathbf{f}_{\alpha\beta}^1, \dots, \mathbf{f}_{\alpha\beta}^{N_t-1}], \quad \widehat{\mathbf{X}}_{\alpha\beta} = [\mathbf{f}_{\alpha\beta}^2, \dots, \mathbf{f}_{\alpha\beta}^{N_t}] \quad \mathbf{f}_{\alpha\beta}^n \in \mathbb{R}^{N_r N_g}$
- $\tilde{\mathbf{B}} = \hat{\mathbf{X}}\mathbf{X}^+$ is the closest approximation to **B** in the Frobenius norm. Here + signifies the Moore-Penrose pseudo inverse.
- The DMD representation

$$\mathcal{A}_k^{\mathfrak{f}_{lphaeta}} = \{ ilde{eta}_\ell, ilde{oldsymbol{arphi}}_\ell, \hspace{0.2cm} ilde{f{f}}_{lphaeta}(t^n) = \sum_{\ell=1}^k ilde{eta}_\ell ilde{oldsymbol{arphi}}_\ell e^{ ilde{\omega}_\ell t^n}, \hspace{0.2cm} ilde{\omega}_\ell = \Delta t^{-1} \ln(\gamma_\ell)\,,$$

where $\gamma_\ell, ilde{m{arphi}}_\ell$ are the eigenvalues and associated eigenfunctions of $ilde{m{B}}$

- Equilibrium-subtracted DMD (DMD-E)
 - $\circ~$ Construction of the linear operator B that fits the equilibrium-subtracted data
 - The time-dependent TRT problem tends to steady-state as $t \to \infty$.

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Determination of Rank

- For each data matrix **A**, the rank k must be calculated to store A_k
- We consider the rank-k truncated SVD

$$\mathbf{A} \approx \mathbf{A}_k = \mathbf{U}_k \mathbf{S}_k \mathbf{V}'_k$$
$$\mathbf{U}_k = [\mathbf{u}_1 \dots \mathbf{u}_k], \quad \mathbf{S}_k = \text{diag}(\sigma_1, \dots, \sigma_k), \quad \mathbf{V}_k = [\mathbf{v}_1 \dots \mathbf{v}_k]$$

The error in Frobenius norm

$$\|\mathbf{A}-\mathbf{A}_k\|_F^2 = \sum_{\ell=k+1}^d \sigma_\ell^2$$

• We calculate k by choosing the relative Frobenius norm error $\xi_{\rm rel}$

$$\xi_{\rm rel}^2 = \frac{\sum_{\ell=k+1}^{d} \sigma_{\ell}^2}{\sum_{\ell=1}^{d} \sigma_{\ell}^2} = \frac{\|\mathbf{A} - \mathbf{A}_k\|_F^2}{\|\mathbf{A}\|_F^2}$$

- k increases as ξ_{rel} decreases
 - Increasing k increases cost in calculating approximate closures
 - Accuracy is also expected to increase with k

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- We do not have theory to predict how the models will perform
- Numerical testing is used to demonstrate the following
 - The models converge to the reference solution as k
 ightarrow d
 - How the ROM errors converge as $k \rightarrow d$
 - How well the *low-rank* ROMs capture fundamental physics in the solution compared to the full-order TRT model on a given phase-space and time

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Numerical Test Problem



• We test this method on a 2D extension of the Fleck-Cummings (F-C) test

- Fully-implicit time integration
- BTE discretized with simple corner balance scheme
- All low-order equations discretized with 2nd order finite volumes
- Grid:
 - 20x20 spatial cells, 17 groups, 144 discrete directions
 - 300 time steps $\Delta t = .02$ ns for $0 \le t \le 6$ ns
- Degrees of freedom: 1.175×10^9
- ROM degrees of freedom: 1.728×10^7

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Numerical Results (POD)

- Databases are formed from the full-order model solution
- Ranks of approximation and memory requirements for the POD with varying $\xi_{\rm rel}$



Numerical Results (POD)

- Relative errors in the 2-norm using the POD compared to the full-order solution
- Errors plotted vs time, each curve corresponds to a value for $\xi_{\rm rel}$



Material Temperature

Radiation Energy Density

Numerical Results (DMD)

- Relative errors in the 2-norm using the DMD compared to the full-order solution
- Errors plotted vs time, each curve corresponds to a value for $\xi_{\rm rel}$



Numerical Results (DMD-E)

- Relative errors in the 2-norm using the DMD-E compared to the full-order solution
- Errors plotted vs time, each curve corresponds to a value for $\xi_{\rm rel}$



Convergence of the ROM with Rank (POD)

- Relative errors in the 2-norm using the POD compared to the full-order solution
- Errors plotted vs ξ_{rel} , each curve corresponds to an instant of time



Convergence of the ROM with Rank (DMD)

- Relative errors in the 2-norm using the DMD compared to the full-order solution
- Errors plotted vs $\xi_{\rm rel}$, each curve corresponds to an instant of time



Convergence of the ROM with Rank (DMD-E)

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- Relative errors in the 2-norm using the DMD-E compared to the full-order solution
- Errors plotted vs ξ_{rel} , each curve corresponds to an instant of time



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Conservation of Physics: Breakout Time

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- To demonstrate how the low-rank ROMs conserve fundamental physics in the TRT solution, we consider breakout time
- Breakout time is an important measurement in high-temperature laser-driven radiation shock experiments
- For the F-C test we can calculate how well the ROMs capture certain quantities on the right boundary as time elapses
- Total radiation energy density (\bar{E}_R) and material temperature (\bar{T}_R) averaged over the right boundary of the spatial domain vs time

$$\bar{T}_R = rac{1}{L_R} \int_0^{L_R} T(x_R, y) \ dy \,, \quad \bar{E}_R = rac{1}{L_R} \int_0^{L_R} E(x_R, y) \ dy$$

• We also consider the spectrum of radiation present at the right boundary

$$\bar{E}_{R,g} = \frac{1}{L_R} \int_0^{L_R} E_g(x_R, y) \ dy$$

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Breakout Time: FOM

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• Total radiation energy density (\bar{E}_R) and material temperature (\bar{T}_R) averaged over the right boundary of the spatial domain vs time



Breakout Time: Relative Error for the ROMs

•
$$\xi_{rel} = 10^{-4}$$

$$\bar{T}_R = \frac{1}{L_R} \int_0^{L_R} T(x_R, y) \, dy \,, \quad \bar{E}_R = \frac{1}{L_R} \int_0^{L_R} E(x_R, y) \, dy$$



Breakout Time: Relative Error for the DDET ROMs



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•
$$\xi_{\rm rel} = 10^{-4}$$

$$\bar{E}_{R,g} = \frac{1}{L_R} \int_0^{L_R} E_g(x_R, y) \, dy$$



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Conclusion

- Main elements of the developed methodology
 - nonlinear projection of the BTE and formulation of a hierarchy of low-order moment equations
 - data-driven techniques to approximate closures
- All models require data on the BTE solution
- The proposed methods have been shown to perform well on highly nonlinear thermal radiative transfer problems
- Any multiphysical equations of interest can be coupled with the effective grey QD equations
- Use of the low-order moment equations enforces conservation of fundamental physics in radiative transfer component
- The proposed approach for development of ROMs can be applied to a wide class of multiphysical high-energy density problems, such as radiative hydrodynamics problems.
- Future research items
 - Optimal sampling techniques for generation of data to inform and train ROMs for TRT
 - Investigion of more complex data-driven methods for approximation
 - Parametrized ROMs for TRT

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